

Shear viscosity of a granular fluid

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I. Undriven Uniform Shear Flow

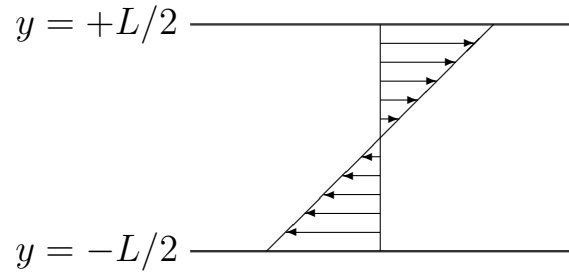
- One of the simplest nonequilibrium states: **Uniform Shear Flow (USF)**

- At a *macroscopic* level, the USF is characterized by

$$u_x = ay, \quad a = \text{constant shear rate}$$

$$n = \text{const}$$

$$\nabla T = 0$$



- In the local Lagrangian frame, the velocity distribution function becomes *uniform*:

$$f(\mathbf{r}, \mathbf{v}, t) = f(\mathbf{V}, t), \quad \mathbf{V} \equiv \mathbf{v} - \mathbf{u}$$

Molecular fluid (elastic collisions)

- Energy balance equation \Rightarrow Viscous heating:

$$\partial_t T = - \underbrace{\frac{2}{3n} a P_{xy}}_{\text{viscous heating}}, \quad P_{ij} = \text{pressure tensor}$$

- Low-density gas of hard spheres [Gómez-Ordóñez *et al.*, PRA **39**, 3038 (1989)]:

- Collision frequency grows with time: $\nu(t) \propto [T(t)]^{1/2}$ (hard spheres)
- Reduced shear rate: $a^*(t) \equiv \frac{a}{\nu(t)} \xrightarrow{t \rightarrow \infty} 0$
- This is an efficient way of measuring the *Navier-Stokes* shear viscosity $\eta_0(n, T)$, as first proposed by Naitoh & Ono (1979):

$$\begin{aligned}
 & -a^{-1}P_{xy}(t) \rightarrow \eta_0(n, T(t)) \\
 \Rightarrow & -\frac{\nu(t)}{a} \frac{P_{xy}(t)}{nT(t)} \xrightarrow{t \rightarrow \infty} \frac{\nu(t)}{nT(t)} \eta_0(n, T(t)) = \eta_0^*(\phi)
 \end{aligned}$$

- For instance, at a packing fraction $\phi \equiv (\pi/6)n\sigma^3 = 0.42$ [Montanero & Santos, PRE **54**, 438 (1996)],

Granular fluid (inelastic collisions)

- Now, the inelasticity of collisions provides an energy sink:

$$\partial_t T = \underbrace{-\frac{2}{3n} a P_{xy}}_{\text{viscous heating}} + \underbrace{(-\zeta T)}_{\text{inelastic cooling}}, \quad \zeta = \text{cooling rate} \propto T^{1/2}(1 - \alpha^2)$$

- A steady state is eventually reached in which the viscous heating is exactly balanced by collisional cooling effects:

$$-\frac{P_{xy}}{nT} \rightarrow \frac{3\zeta}{2a}$$

- Dimensional analysis:

$$-\frac{P_{xy}}{nT} = F(\phi, \alpha) \Rightarrow \begin{cases} T = \theta(\phi, \alpha) m \sigma^2 a^2 \propto a^2 \\ -P_{xy} = \phi^{-1} \tau_{xy}(\phi, \alpha) m n \sigma^2 a^2 \propto a^2 \end{cases}$$

Highly non-Newtonian behavior!

- Functions $\theta(\phi, \alpha)$ and $\tau_{xy}(\phi, \alpha)$ [Montanero *et al.* JFM **389**, 391 (1999)]:

II. Driven Uniform Shear Flow

- Thus, in the (undriven) USF for granular fluids, $-P_{xy} \propto a^2$.
- Is it possible to “frustrate” the cooling effects so that viscous heating dominates and $-P_{xy} \propto a$ for long times, as in the case of molecular fluids?
- If so, one could identify a (linear) shear viscosity as

$$\begin{aligned}
 & -a^{-1}P_{xy}(t) \rightarrow \eta(\alpha; n, T(t)) \\
 \Rightarrow & -\frac{\nu(t)}{a} \frac{P_{xy}(t)}{nT(t)} \xrightarrow{t \rightarrow \infty} \frac{\nu(t)}{nT(t)} \eta(\alpha; n, T(t)) = \eta^*(\alpha, \phi)
 \end{aligned}$$

- How different is $\eta^*(\alpha, \phi)$ from $\eta^*(\alpha = 1, \phi) \equiv \eta_0^*(\phi)$?
- To answer these questions, let us assume that the granular fluid is excited by an external energy source that exactly compensates for the collisional loss:

$$\partial_t T = \underbrace{-\frac{2}{3n} a P_{xy}}_{\text{viscous heating}} + \underbrace{(-\zeta T)}_{\text{inelastic cooling}} + \underbrace{\zeta T}_{\text{external source}}$$

- The simplest choice for such an excitation is an “anti-drag” force of the form

$$\mathbf{F}_{\text{exc}} = \frac{1}{2} \zeta (\mathbf{v} - \mathbf{u})$$

- In the absence of shear ($a = 0$, HCS), \mathbf{F}_{exc} *does not* affect the dynamics of the system since it is equivalent to a rescaling of the velocities of the particles.

III. Enskog Theory

- The Enskog equation for inelastic hard spheres under USF is

$$\partial_t f + \underbrace{(-aV_y \partial_{V_x} f)}_{\text{inertial force}} + \underbrace{\frac{\zeta}{2} \partial_{\mathbf{V}} \cdot \mathbf{V} f}_{\text{external excitation}} = \underbrace{J^E[\mathbf{V}|f]}_{\text{inelastic collisions}}$$

where

$$J^E[\mathbf{V}|f] = \sigma^2 \chi(n) \int d\mathbf{V}_1 \int d\hat{\boldsymbol{\sigma}} \Theta(\hat{\boldsymbol{\sigma}} \cdot \mathbf{g}) (\hat{\boldsymbol{\sigma}} \cdot \mathbf{g}) [\alpha^{-2} f(\mathbf{V}', t) f(\mathbf{V}'_1, t) - f(\mathbf{V}, t) f(\mathbf{V}_1, t)]$$

$$\mathbf{g} = \mathbf{V} - \mathbf{V}_1 - \sigma a \hat{\boldsymbol{\sigma}}_y \hat{\mathbf{x}},$$

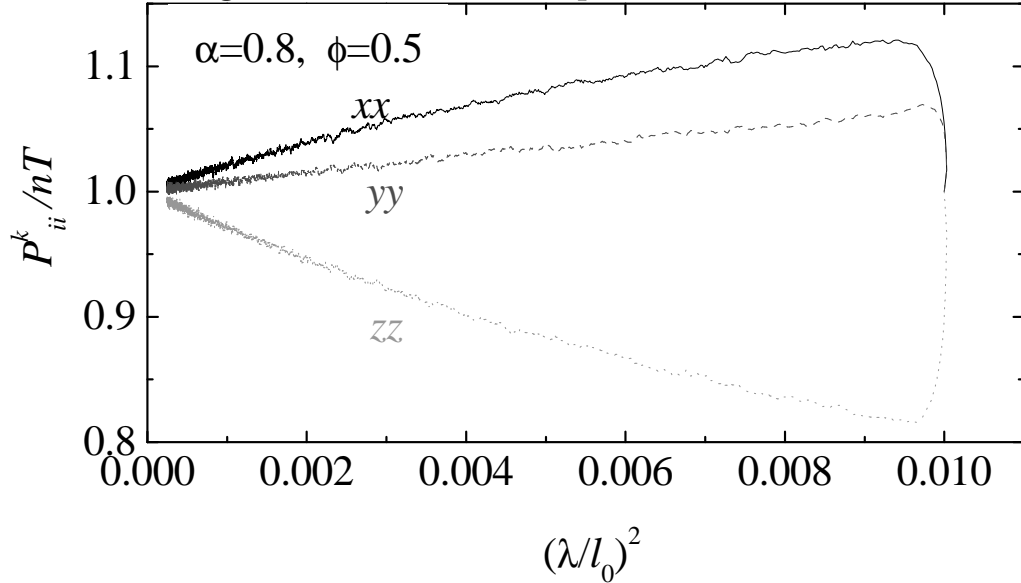
$$\mathbf{V}' = \mathbf{V} - \frac{1 + \alpha^{-1}}{2} (\hat{\boldsymbol{\sigma}} \cdot \mathbf{g}) \hat{\boldsymbol{\sigma}}, \quad \mathbf{V}'_1 = \mathbf{V}_1 + \frac{1 + \alpha^{-1}}{2} (\hat{\boldsymbol{\sigma}} \cdot \mathbf{g}) \hat{\boldsymbol{\sigma}} + 2\sigma a \hat{\boldsymbol{\sigma}}_y \hat{\mathbf{x}}$$

- Our aim is to get $\eta^*(\alpha, \phi)$ by a two-fold route:

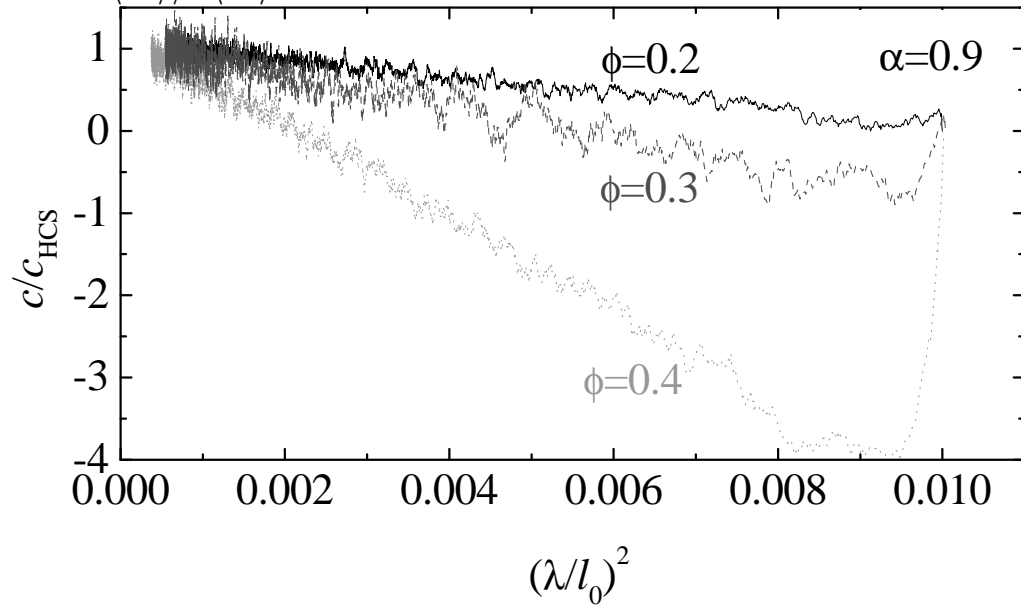
1. Monte Carlo simulations by a variant of the DSMC method [Montanero & Santos, PF **9**, 2057 (1997)].
2. Perturbation analysis around the HCS + Sonine approximation.

Monte Carlo simulations

- Time is monitored by $\lambda/l_0 \propto a^*$, where $\lambda = [\sqrt{2\pi n\sigma^2\chi(n)}]^{-1}$ is the mean free path and $l_0 = \sqrt{2T/m}/a$ is the characteristic hydrodynamic length, which increases (almost linearly) with time.
- Kinetic part of the diagonal elements of the pressure tensor:



- Cumulant $c = 3\langle v^4 \rangle / 5\langle v^2 \rangle^2 - 1$:



- Marginal distribution functions:

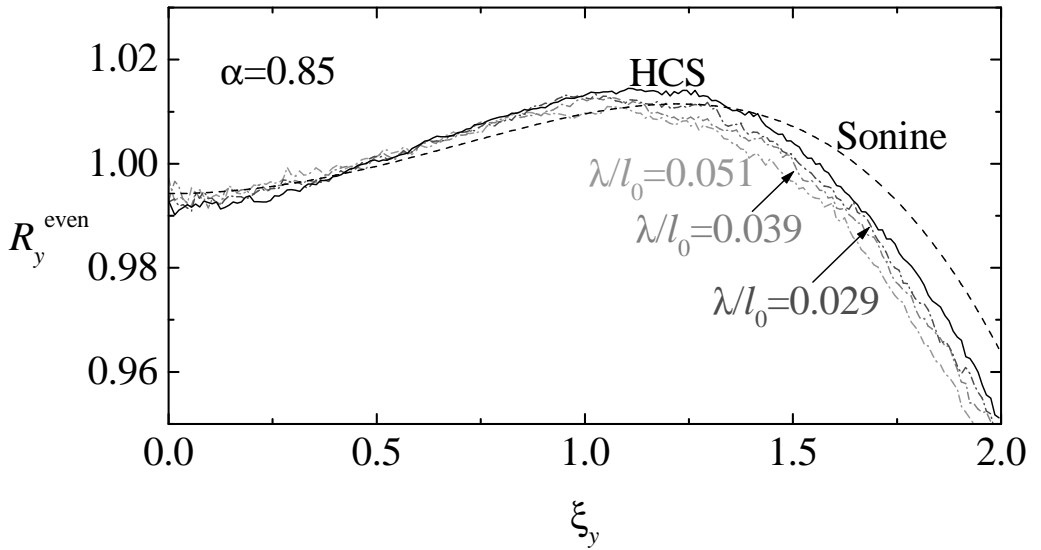
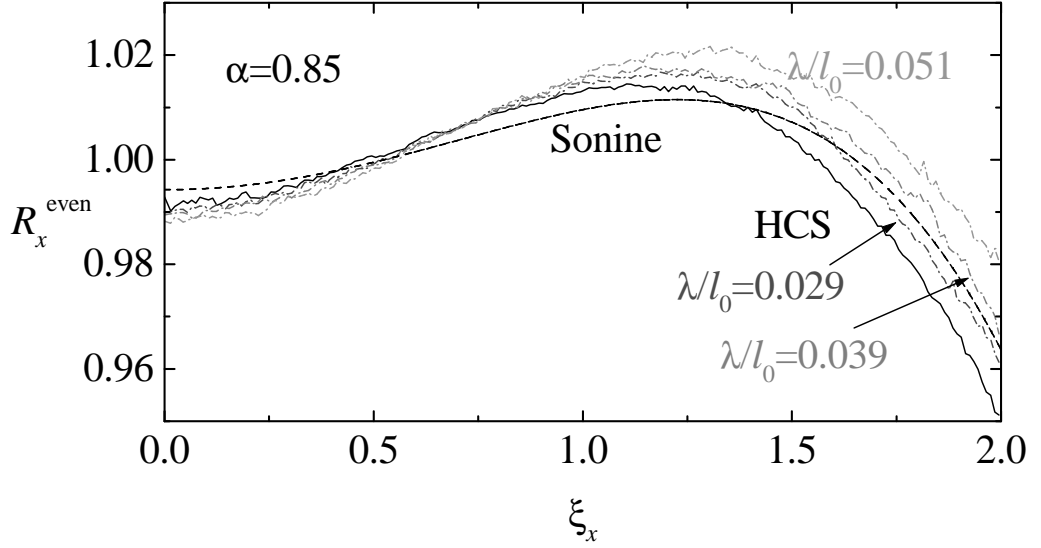
$$\varphi_x(V_x, t) = \int_0^\infty dV_y \int_{-\infty}^\infty dV_z f(\mathbf{V}, t)$$

- Even and odd parts:

$$\varphi_x^{\text{even}}(V_x, t) = \frac{1}{2} [\varphi_x(V_x, t) + \varphi_x(-V_x, t)], \quad \varphi_x^{\text{odd}}(V_x, t) = \frac{1}{2} [\varphi_x(V_x, t) - \varphi_x(-V_x, t)]$$

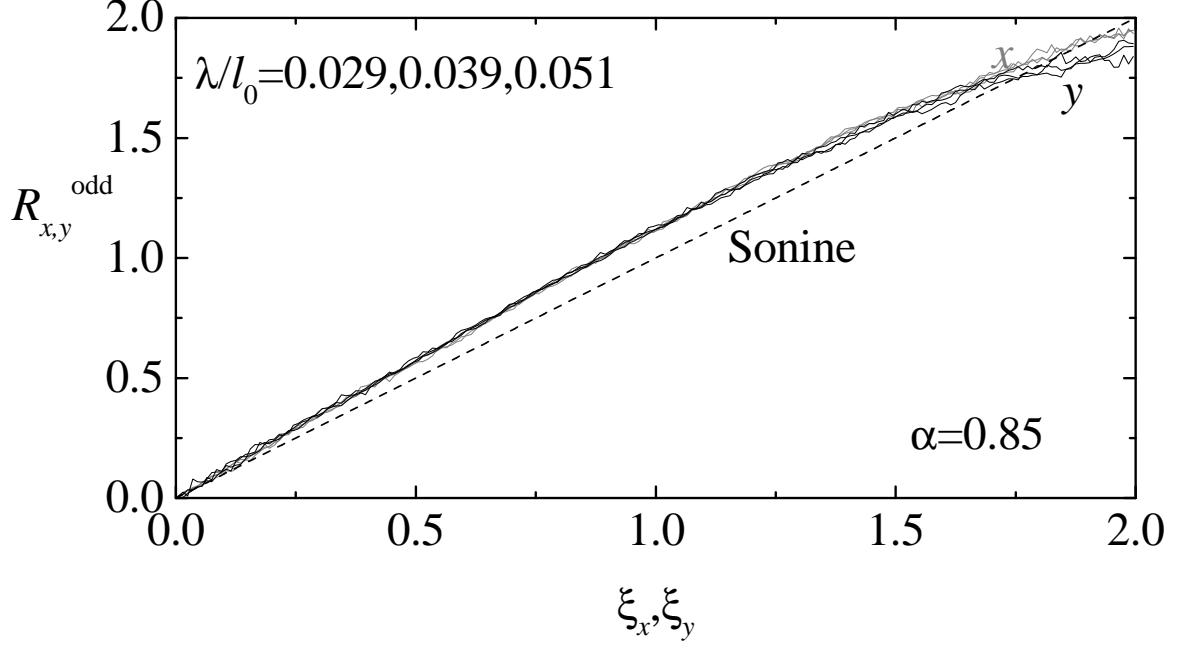
- Normalized even distribution:

$$R_x^{\text{even}}(\xi_x) = \frac{\varphi_x^{\text{even}}(V_x, t)}{\varphi_x^{\text{MB}}(V_x, t)}, \quad \xi_x = V_x / \sqrt{2T/m}$$



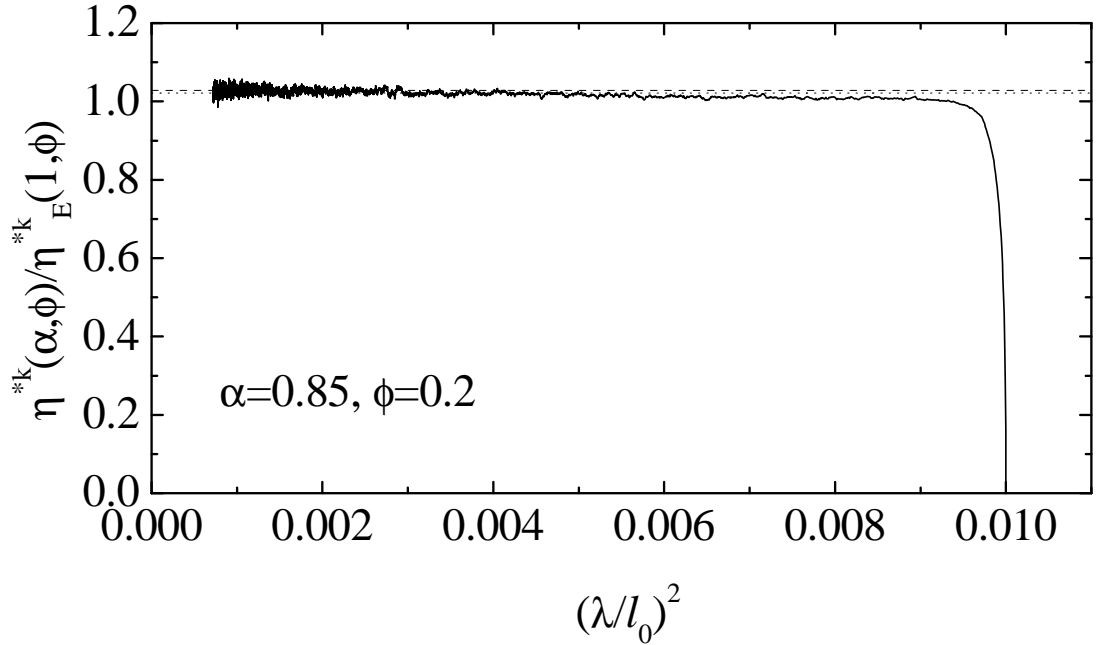
- Normalized odd distribution:

$$R_x^{\text{odd}}(\xi_x) = \frac{\varphi_x^{\text{odd}}(V_x, t) \sqrt{\pi} n T(t)}{\varphi_x^{\text{MB}}(V_x, t) 2P_{xy}^k(t)}$$



- Time evolution of the (kinetic part of the) viscosity:

$$\eta^{*k} = -\frac{\nu(t) P_{xy}^k(t)}{a n T(t)}$$



Perturbation analysis

- Kinetic equation:

$$\partial_t f + (-aV_y \partial_{V_x} f) + \frac{\zeta}{2} \partial_{\mathbf{V}} \cdot \mathbf{V} f = J^E[\mathbf{V}|f]$$

- Perturbation expansion (*à la* Chapman-Enskog) in powers of the shear rate:

$$f(\mathbf{V}) = \underbrace{f_0(\mathbf{V})}_{\text{HCS}} + \underbrace{f_1(\mathbf{V})}_{\mathcal{O}(a)} + \mathcal{O}(a^2)$$

$$J^E[\mathbf{V}|f] = \underbrace{J_0^E[\mathbf{V}|f_0]}_{\text{HCS}} + \underbrace{J_1^E[\mathbf{V}|f_0] - \mathcal{L}f_1(\mathbf{V})}_{\mathcal{O}(a)} + \mathcal{O}(a^2)$$

$$\zeta = \underbrace{\zeta_0}_{\text{HCS}} + \mathcal{O}(a^2)$$

$$\partial_t = \mathcal{O}(a^2)$$

- Zeroth order:

$$\frac{\zeta_0}{2} \partial_{\mathbf{V}} \cdot \mathbf{V} f_0 = J_0^E[\mathbf{V}|f_0]$$

- First order:

$$aV_y \partial_{V_x} f_0 + J_1^E[\mathbf{V}|f_0] = \left(\mathcal{L} + \frac{\zeta_0}{2} \partial_{\mathbf{V}} \cdot \mathbf{V} \right) f_1$$

- Sonine approximation:

$$f_0(\mathbf{V}) \rightarrow f_{\text{MB}}(\mathbf{V}) [1 + c(\alpha)S_2(\xi^2)], \quad S_2(x) = \frac{1}{2}x^2 - \frac{5}{2}x + \frac{15}{8}$$

$$f_1(\mathbf{V}) \rightarrow -\frac{m\alpha\eta^k}{nT^2}f_{\text{MB}}(\mathbf{V})V_xV_y$$

- This allows us to get explicit expressions for the transport coefficients $\eta^{*k}(\alpha, \phi)$ and $\eta^*(\alpha, \phi)$.
- The theory predicts that the shear viscosity of the inelastic system is larger than that of the elastic system at the same density, $\eta^*(\alpha, \phi) > \eta^*(1, \phi)$, if the packing fraction is smaller than a threshold value, $\phi < \phi_0(\alpha)$, while the opposite happens if $\phi > \phi_0(\alpha)$.

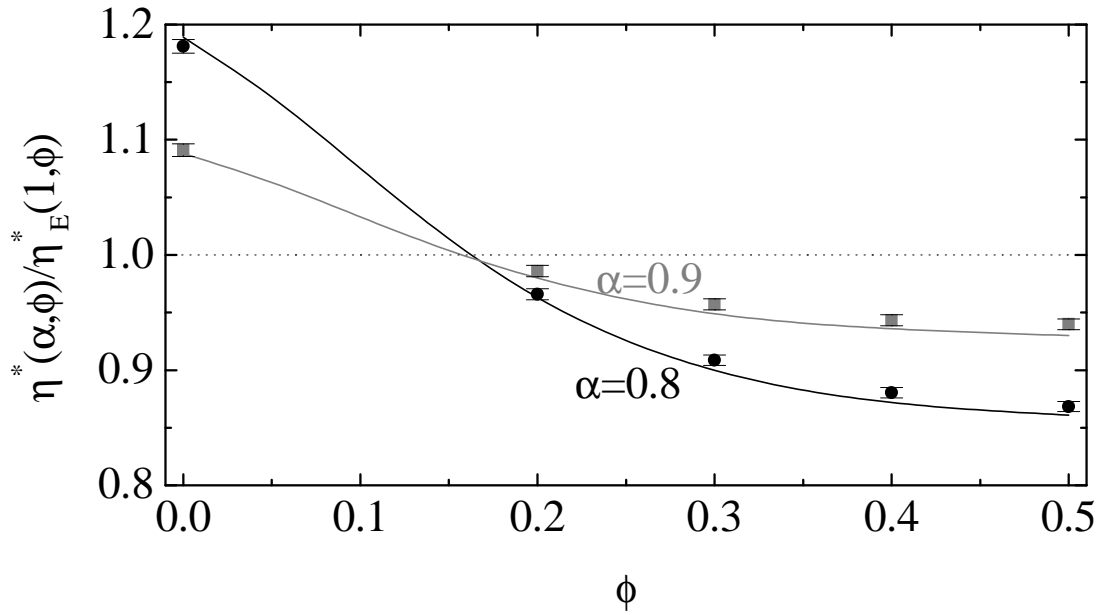
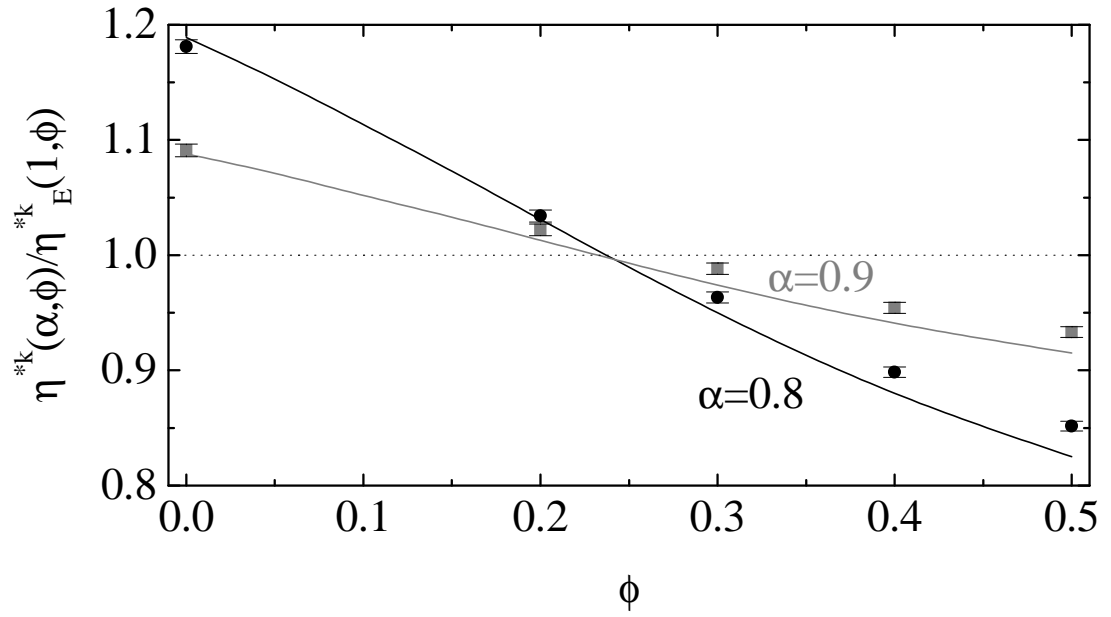
Similar threshold values $\phi_0^k(\alpha)$ and $\phi_0^c(\alpha)$ exist for the kinetic and collisional parts of the shear viscosity.

- In the range $0.8 \leq \alpha \leq 1$ the threshold values are practically independent of the coefficient of restitution:

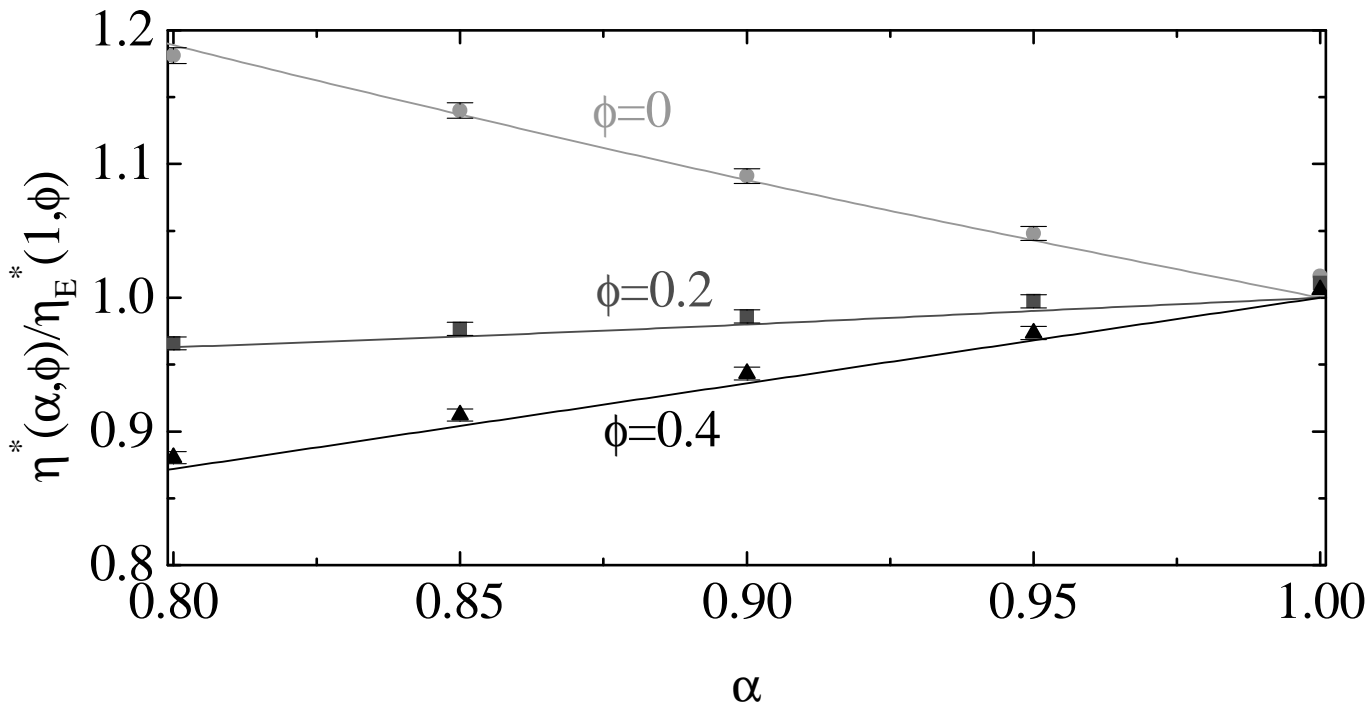
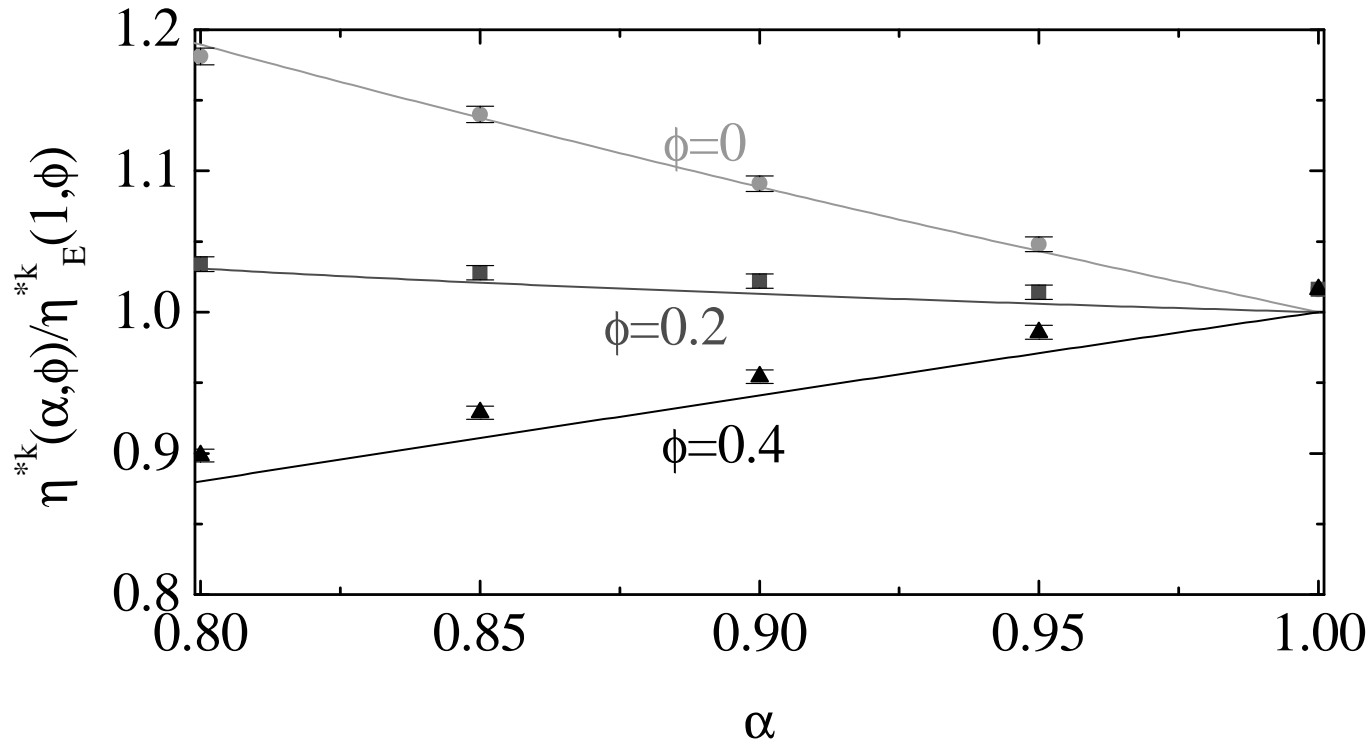
$$\phi_0(\alpha) \simeq 0.16, \quad \phi_0^k(\alpha) \simeq 0.23, \quad \phi_0^c(\alpha) \simeq 0.05$$

IV. Results

- Density dependence:



- Coefficient of restitution dependence:



V. Conclusions

- A driven system of inelastic hard spheres under USF reaches for long times a hydrodynamic regime in which the shear stress is proportional to the shear rate, $P_{xy} = -\eta a$. The proportionality constant defines a shear viscosity coefficient $\eta(\alpha; n, T)$ as a material function of the coefficient of restitution, density, and temperature.
- Comparison between Monte Carlo simulation data and theoretical results obtained from a perturbation analysis (plus a Sonine approximation) shows an excellent agreement.
- The granular fluid is less (more) viscous than the corresponding molecular one if the packing fraction is larger (smaller) than about 16%.
- The same type of excitation mechanism is easy to implement in molecular dynamics simulations. This would be an efficient way of measuring the linear shear viscosity $\eta(\alpha; n, T)$ and compare it with the results obtained from the Enskog theory.

- The coefficient $\eta(\alpha; n, T)$ represents the linear shear viscosity of an excited granular fluid under USF. Does it coincide with the *Navier-Stokes* shear viscosity, $\eta_{\text{NS}}(\alpha; n, T)$, characterizing the response of the system to a weak spontaneous inhomogeneity in the velocity field?
- In the latter case, a Chapman-Enskog expansion [Garzó & Dufty, PRE **59**, 5895 (1999)] of the form $f = f_0 + f_{\text{NS}} + \dots$ leads to

$$aV_y \partial_{V_x} f_0 + J_1^E[\mathbf{V}|f_0] = \left(\mathcal{L} + \frac{\zeta_0}{2} \partial_{\mathbf{V}} \cdot \mathbf{V} + \frac{\zeta_0}{2} \right) f_{\text{NS}}$$

while in our problem we had

$$aV_y \partial_{V_x} f_0 + J_1^E[\mathbf{V}|f_0] = \left(\mathcal{L} + \frac{\zeta_0}{2} \partial_{\mathbf{V}} \cdot \mathbf{V} \right) f_1$$

Thus, $f_1 \neq f_{\text{NS}}$ and, consequently, $\eta \neq \eta_{\text{NS}}$.

- In fact, in the Sonine approximation,

$$\frac{1}{\eta_{\text{NS}}^{*k}} = \frac{1}{\eta^{*k}} + \frac{5}{24} (1 - \alpha)^2 \chi(\phi) \frac{1 + \frac{3}{16} c(\alpha)}{1 - \frac{2}{5} (1 + \alpha) (1 - 3\alpha) \phi \chi(\phi)}$$

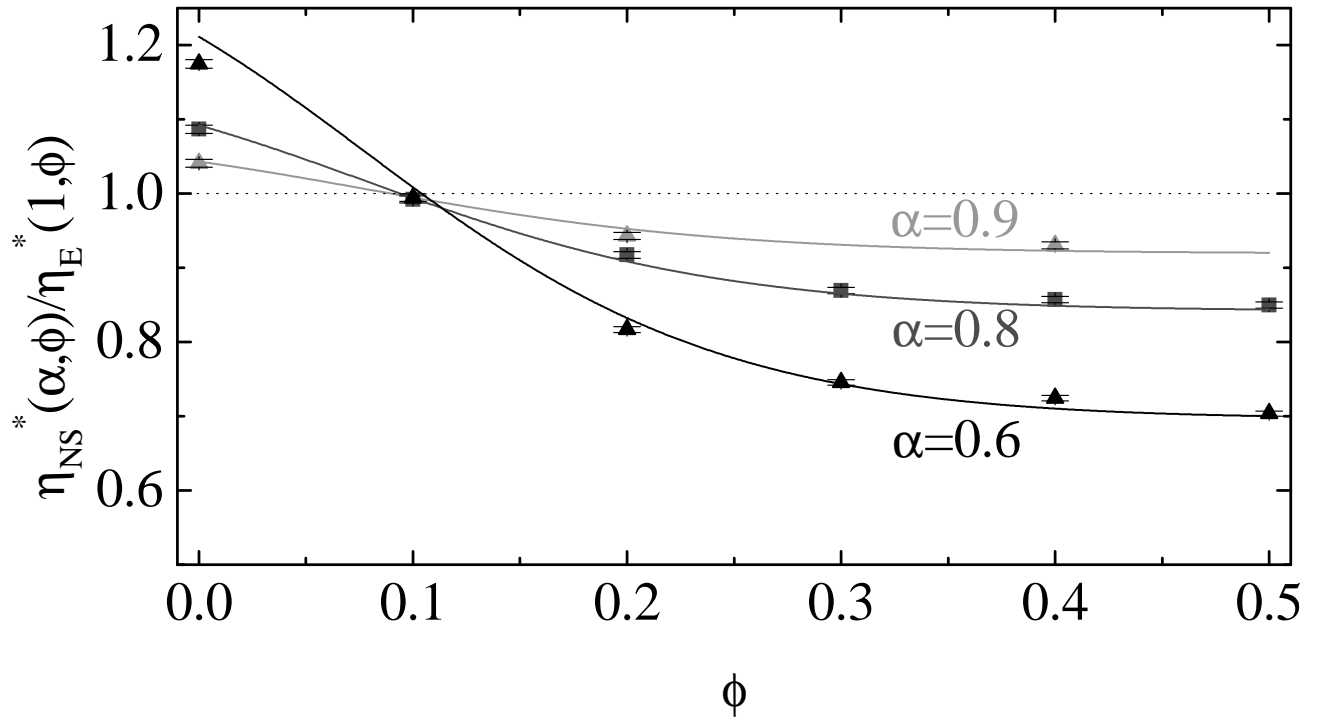
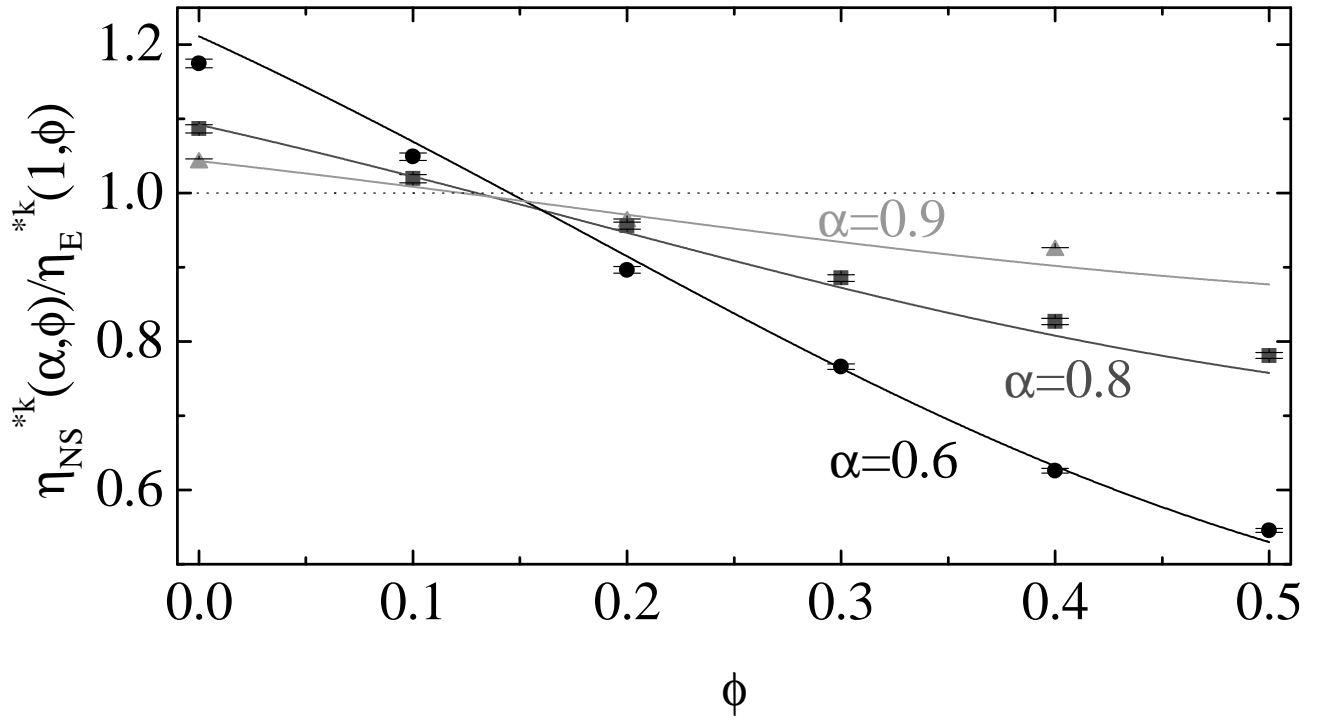
- Is it possible to “retouch” the driven USF problem so that the coefficient η_{NS} , rather than η , can be measured in simulations?

- The simplest possibility is

$$\partial_t f + \underbrace{(-aV_y \partial_{V_x} f)}_{\text{inertial force}} + \underbrace{\frac{\zeta}{2} \partial_{\mathbf{V}} \cdot \mathbf{V} f}_{\text{external excitation}} = \underbrace{J^E[\mathbf{V}|f]}_{\text{inelastic collisions}} - \underbrace{\frac{\zeta}{2} (f - f_0)}_{\text{BGK-like term}}$$

- In the simulations the new term is implemented by randomly choosing a fraction of particles $\zeta \delta t / 2$ in each timestep δt and replacing the velocities of those particles by random velocities drawn from the distribution f_0 .

- Density dependence:



- In this case, $\phi_0(\alpha) \simeq 0.10$, $\phi_0^k(\alpha) \simeq 0.13$, $\phi_0^c(\alpha) = 0$

- Coefficient of restitution dependence:

